

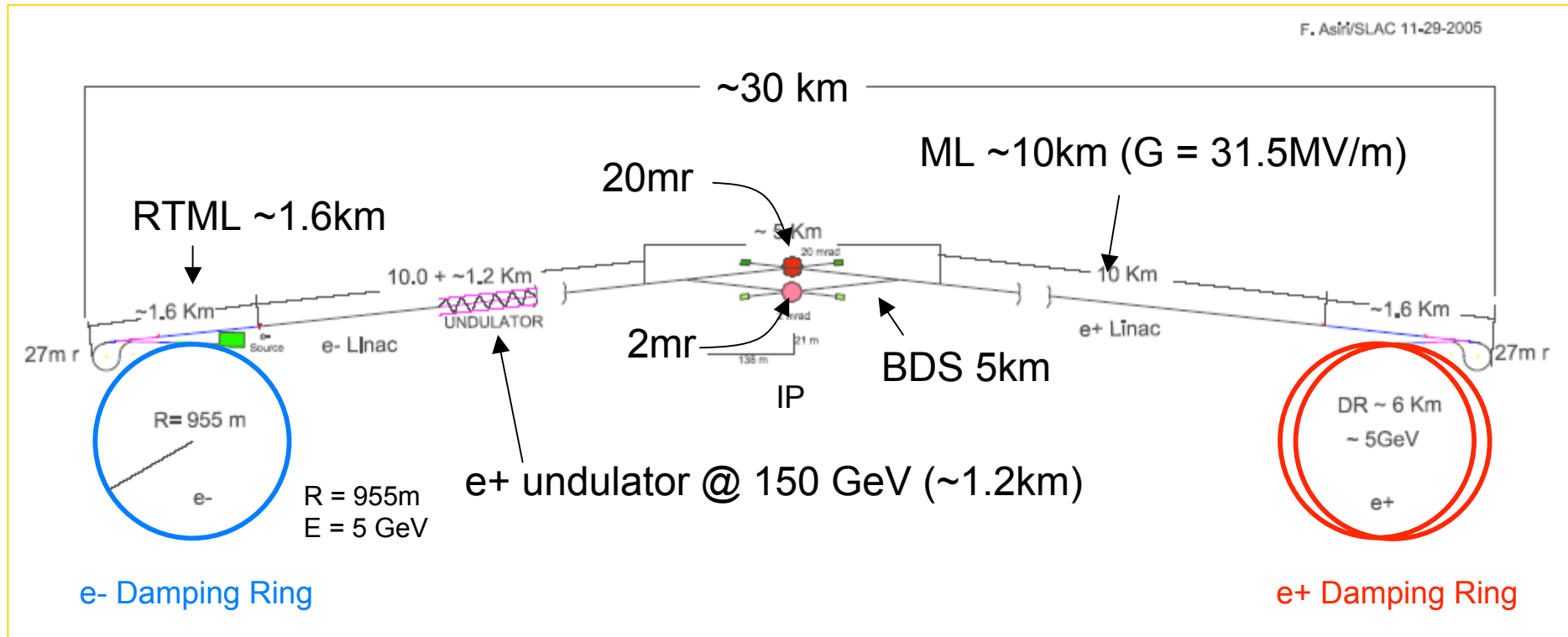
Dynamic Aperture Survey of ILC Damping Ring using SAD

1. Wiggler fringe effect
2. Multipole errors

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2006.09.05

Workshop SAD2006

ILC Baseline Machine (500 GeV)



not to scale

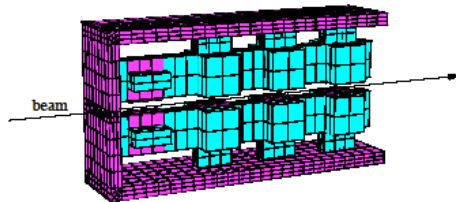
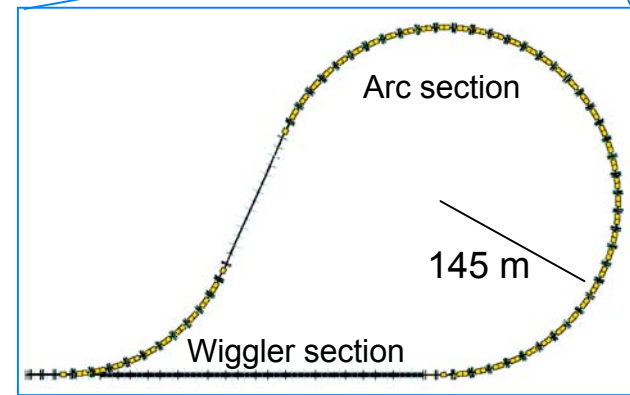


TESLA Dogbone Damping Ring

$C = 17 \text{ km}$ $E = 5 \text{ GeV}$

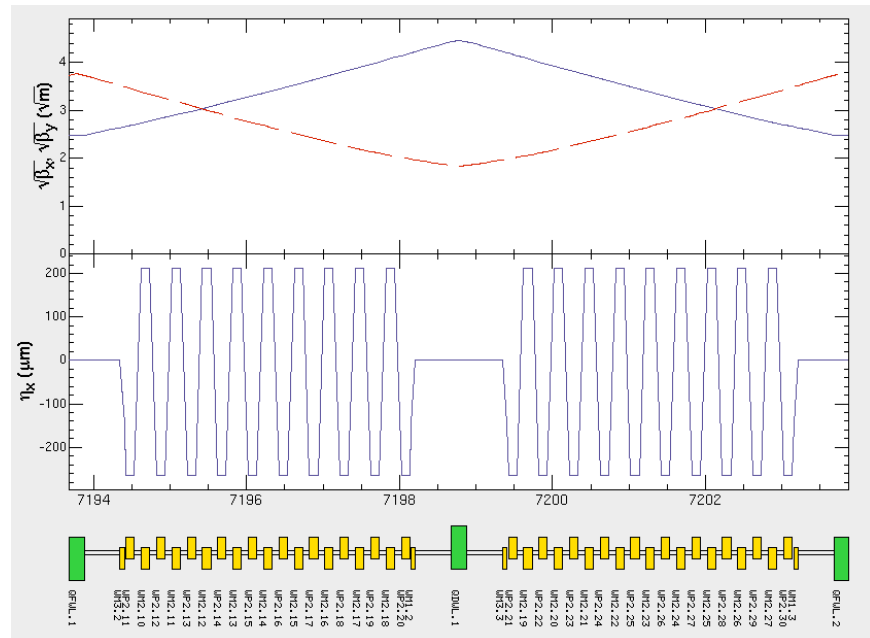
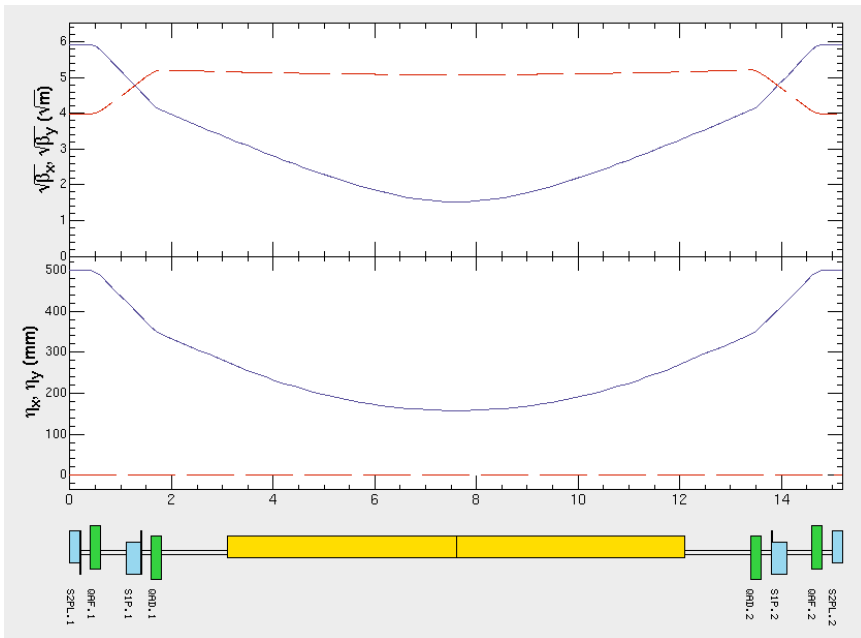
```

$DisplayFunction=CanvasDrawer;
OpticsPlot[{"BX","BY"},{"EX","EY"},Region->{1,100}];
GeometryPlot[Region->{1,100}];
Update[];
    
```

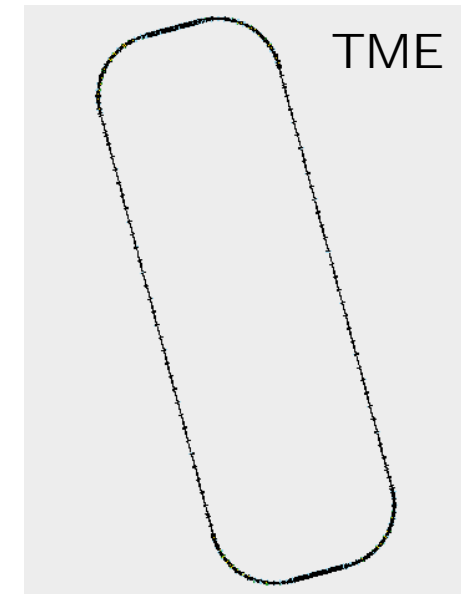


TME lattice

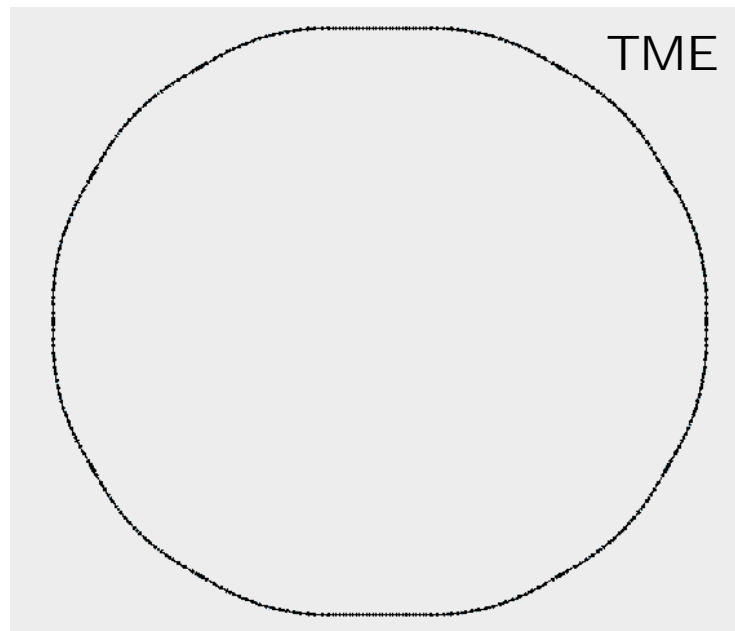
Wiggler cell



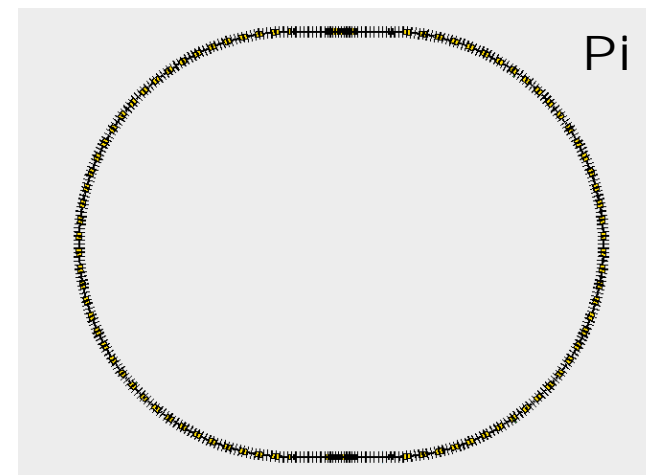
OTW Damping Ring

 $C = 3.2 \text{ km}$ $E = 5 \text{ GeV}$ 

OCS Damping Ring

 $C = 6.5 \text{ km}$ $E = 5 \text{ GeV}$ 

PPA Damping Ring

 $C = 2.8 \text{ km}$ $E = 5 \text{ GeV}$ 

Nonlinear wigglers

SAD can deal with nonlinear wigglers due to fringe field.

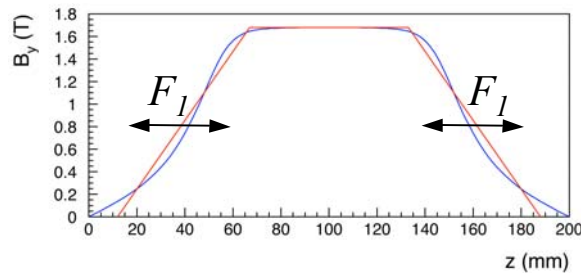
Wigglers (field map):

$$B_0 = 1.68 \text{ T}$$

BEND WP2 =(L =.121 ANGLE =.0106 E1 =.5 E2 =.5 F1=0.055 FRINGE=1);

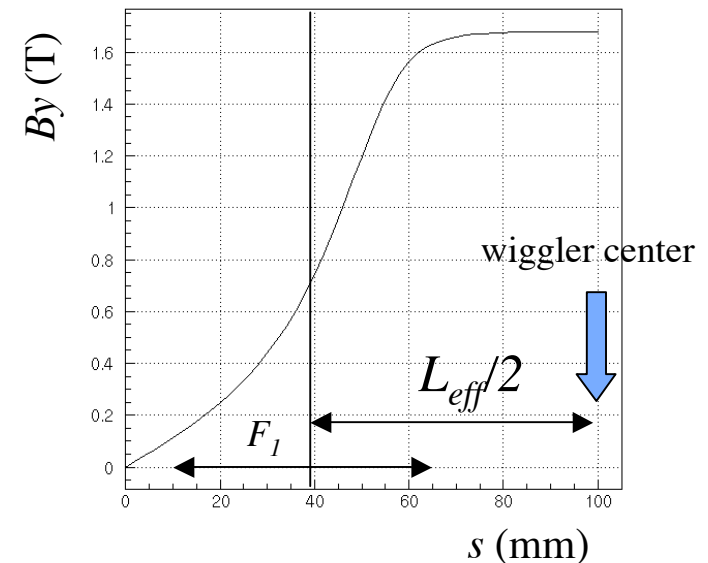
$$\text{Effective length } L_{eff} = 121 \text{ mm}$$

$$\text{Fringe field: } F_1 = 55 \text{ mm}$$



$$F_1 = 6 \int_{-\infty}^{+\infty} \left\{ \frac{B_y(s)}{B_0} - \left(\frac{B_y(s)}{B_0} \right)^2 \right\} ds$$

wiggler field



Wiggler bending field is approximated by trapezoid. Hamiltonian up to $O(y^4)$ is included in SAD.

$$H = H_0 + \frac{L_w}{4\rho_w^2} y^2 + \frac{L_w}{12\rho_w^2} k^2 y^4, \quad k = \frac{2\pi}{\lambda_w} \quad y \approx \sqrt{2J_y \bar{\beta}_y}$$

$$= 4\pi (v_{x0} J_x + v_{y0} J_y + v_{z0} J_z + c_{xx} J_x^2 + c_{yy} J_y^2 + c_{zz} J_z^2 + L)$$

Vertical betatron tune ($J_x = J_z = 0$) analytically:

$$v_y = \frac{1}{4\pi} \frac{\partial H}{\partial J_y} = v_{y0} + 2c_{yy} J_y, \quad c_{yy} = \frac{\bar{\beta}_y^2 L_w k^2}{12\pi \rho_w^2} \quad \dots (1)$$

Nonlinear coefficient: c_{yy}

TESLA Dogbone:

$$\beta_y = 8.7 \text{ m}$$

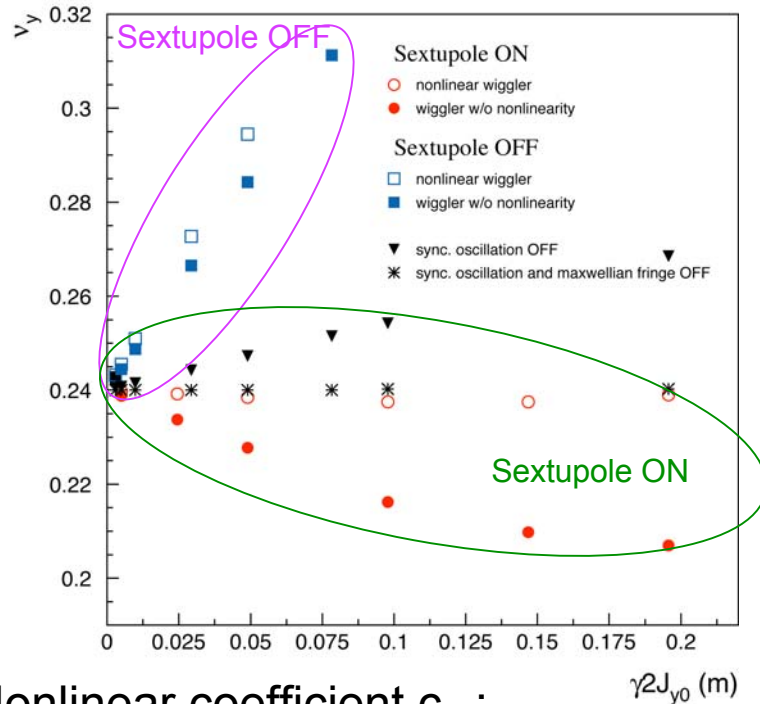
$$L_w = 417 \text{ m}$$

$$\rho_w = 10 \text{ m}$$

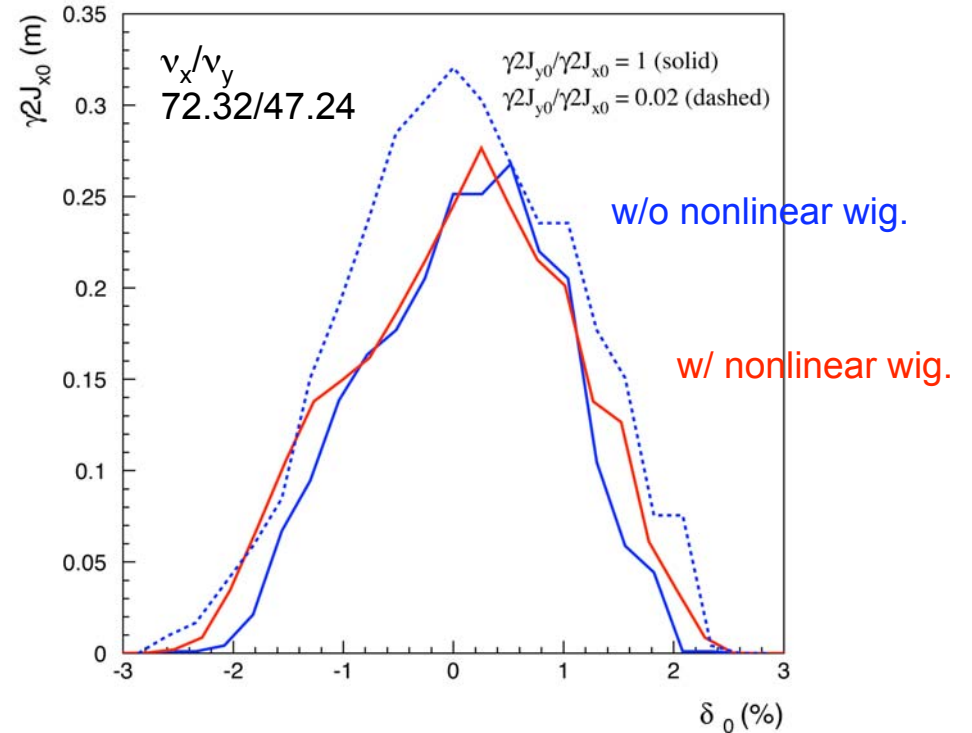
$$\lambda_w = 0.4 \text{ m}$$

Tracking simulations - TESLA Dogbone

Amplitude dependence of vertical tune Tracking simulations



γ2J - δ plot



Nonlinear coefficient c_{yy} :

Sextupole	w/o nonlinear wig. (A)	w/ nonlinear wig. (B)	(B) - (A)	Analytic formula (1)
ON	-2361	-238	+2123	$c_{yy} = +2066$
OFF	+8858	+11061	+2203	

Tracking simulation well reproduces the octupole-like component of the wigglers. There is no significant difference between without and with nonlinear wig. for DA.

Dynamic Aperture Survey with SAD

- 6-dimensional coordinate: $(x, x'=p_x/p_0, y, y'=p_y/p_0, z, \delta=\Delta p/p_0)$
- Survey region is divided by 51 regions.
- Start from the smallest initial amplitudes.
- Maximum initial amplitude is defined by "dynamic aperture" where the particle can circulate stable during the required turns.
- Option (default):

Ring or Transport beam-line	RING	TRPT
Synchrotron radiation	RAD	NORAD
Quantum excitation (need random seeds)	FLUC	NOFLUC
Acceleration by rf cavities	RFSW	NORFSW
COD with/without radiation loss <i>p</i> ₀ changes with energy loss or constant(design value)	RADCOD	NORADCOD

Ordinary dynamic aperture survey uses:
RAD, NOFLUC, RFSW, RADCOD

Multipole errors for magnets

$$B_y + iB_x = B(r_0) \sum_{k=1} (b_k + ia_k)(x + iy)^{k-1} \frac{1}{r_0^{k-1}}$$

	PEP-II	PEP-II		SPEAR3
index	Dipole	Quadrupole		Sextupole
k	b_k/b_1	b_k/b_2	a_k/a_2	b_k/b_3
3	1.6×10^{-4}	-1.24×10^{-5}	-1.15×10^{-5}	
4	-1.6×10^{-5}	2.30×10^{-6}	1.41×10^{-5}	2.0×10^{-4}
5	7.5×10^{-5}	-4.30×10^{-6}	6.20×10^{-7}	1.0×10^{-4}
6		3.40×10^{-4}	-4.93×10^{-5}	7.0×10^{-4}
7		3.00×10^{-7}	-1.02×10^{-6}	1.0×10^{-4}
8		6.00×10^{-7}	3.80×10^{-7}	1.0×10^{-4}
9		6.00×10^{-7}	-2.80×10^{-7}	1.0×10^{-4}
10		-6.17×10^{-5}	-5.77×10^{-5}	1.0×10^{-4}
11		-2.00×10^{-7}	-3.80×10^{-7}	1.0×10^{-4}
12		3.60×10^{-6}	-6.53×10^{-6}	3.2×10^{-3}
13		6.00×10^{-7}	1.20×10^{-6}	
14		1.00×10^{-6}	-7.40×10^{-7}	
r_0 (m)	0.030	0.050		0.032

allowed multipoles

measured data (Y. Cai)

SAD script

Insertion of multipole elements

```
MULT      FQD1=()
          FQF1=()      define MULT components
          :
```

```
;
FFS;
nm=Element["NAME","BE*|Q{DF}*|S{DF}*"];
line=ExtractBeamLine[ringName];
```

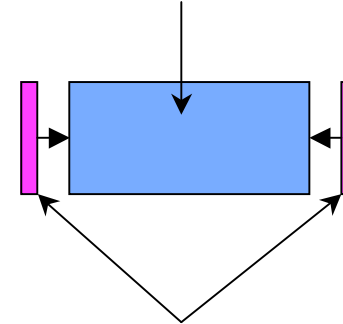
```
Do[
  line=line/.ToExpression[nm[[i]]]->
    BeamLine[ToExpression["F"//nm[[i]],ToExpression[nm[[i]],ToExpression["F"//nm[[i]]]];
  ,{i,1,Length[nm]}];
FFS["visit line;"];
FFS["calc;"];
```

!!! Quadrupole

```
quad=Element["NAME","Q{DF}*"];
aquad={.....};      coefficient:  $a_n$ 
bquad={.....};      coefficient:  $b_n$ 
r0=0.05;            bore radius:  $r_0$ 
mm=1;
Do[
```

```
  Scan[(Element["K"//nn,"F"//#]=0.5*Element["K1",#]*Factorial[nn]*bquad[[nn+1]]/r0^(nn-mm))&,quad];
  Scan[(Element["SK"//nn,"F"//#]=0.5*Element["K1",#]*Factorial[nn]*aquad[[nn+1]]/r0^(nn-mm))&,quad];
  ,{nn,2,13}];
```

Bend, Quad, Sextupole



multipole elements(L=0)

Dynamic Aperture Survey - ILC Damping Ring

- Dynamic Aperture
 - Tracking simulations ($x, x'=p_x/p_0, y, y'=p_y/p_0, z, \delta=\Delta p/p_0$)
 - Stability during one betatron damping time
 - Dynamic aperture is reduced due to nonlinear field of sextupoles and wigglers.

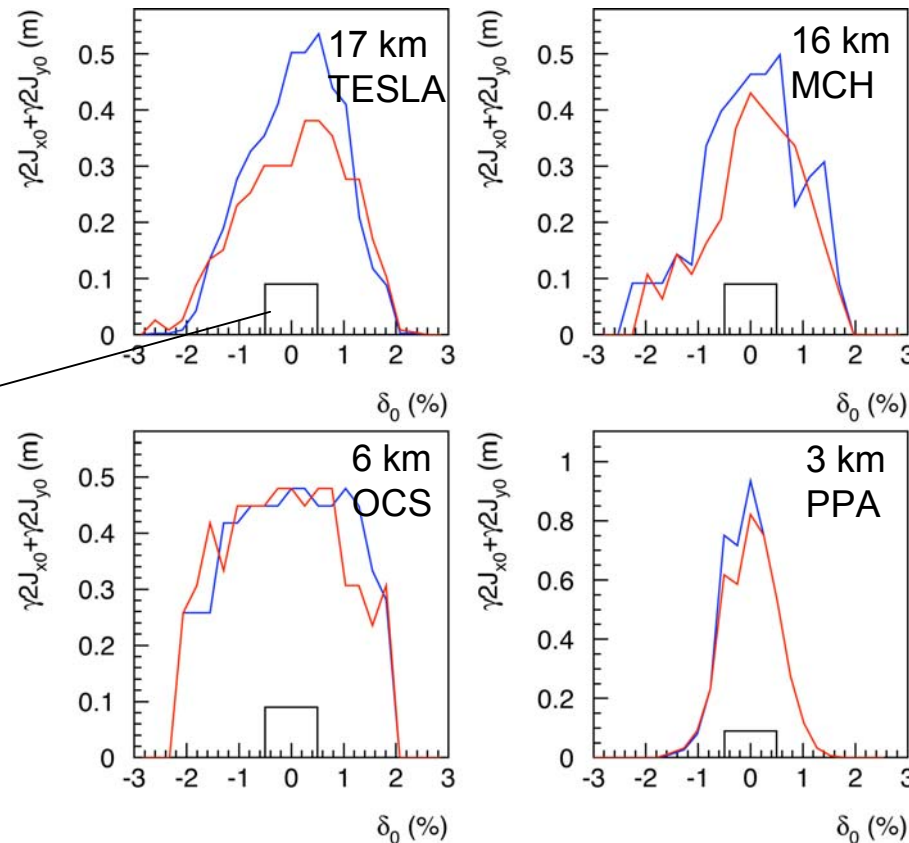
No machine error

Machine errors
with multipole errors

Required
aperture

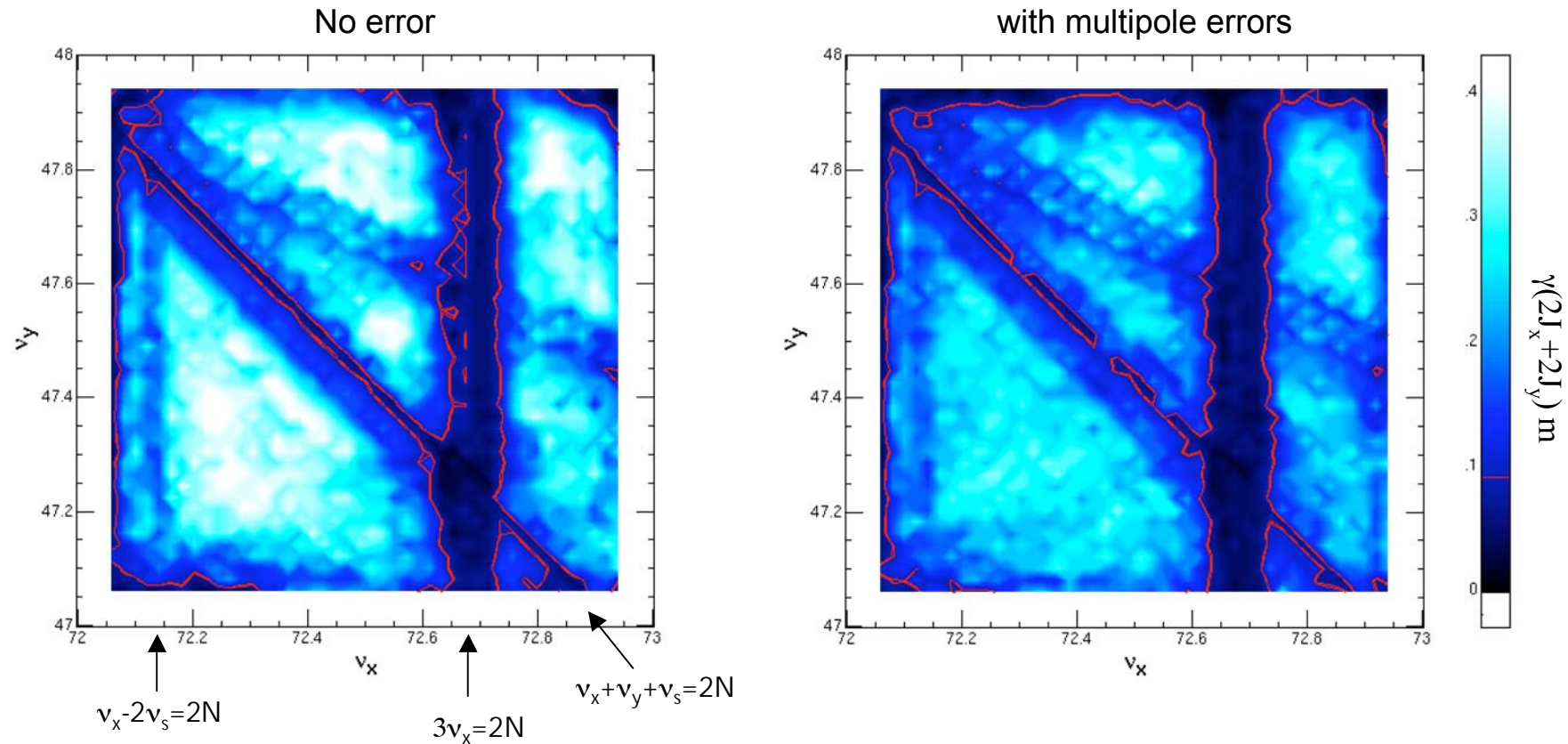
$$\gamma(2J_x + 2J_y) = 0.09 \text{ m}$$

$$|\delta| = 0.5 \%$$



Tune Survey of ILC Damping Ring

- TESLA Dogbone (17 km)

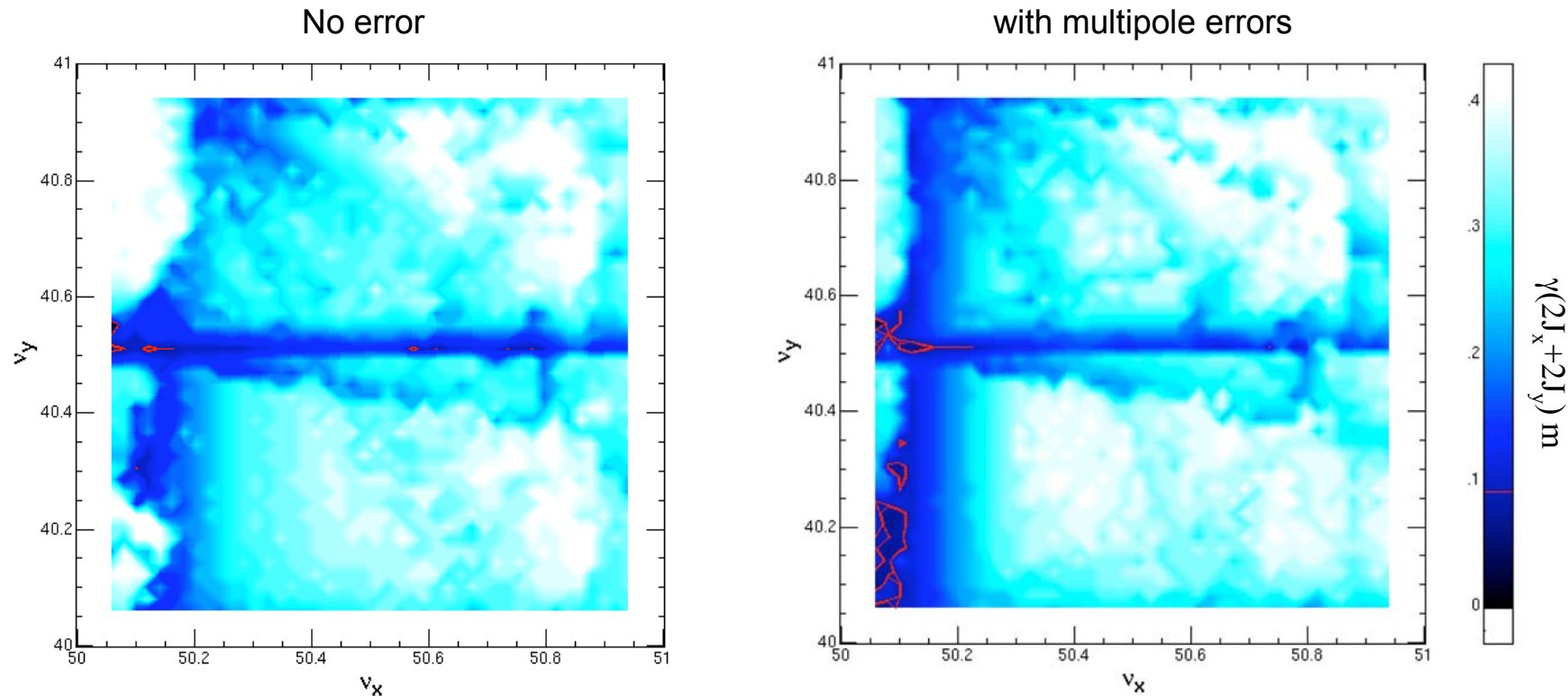


Smallest dynamic aperture with $|\delta| < 0.5\%$ for each tune

Lighter color indicates larger dynamic aperture.

Tune Survey of ILC Damping Ring

- OCS (6.5 km)



```
g=ListContourPlot[score,
  PlotRange->{0.0,0.4},
  MeshRange->{{Nux1-Dnux/2,Nux2+Dnux/2},{Nuy1-Dnuy/2,Nuy2+Dnuy/2}},
  FrameLabel->{"fn`n`dx`n","fn`n`dy`n"},
  ContourColorFunction->colfx,Contours->100,DisplayFunction->Identity];
```

Summary

- Dynamic aperture survey
 - `DynamicApertureSurvey[]`;
- Wiggler fringe field
 - F1
- Multipole errors
 - MULT
- Tune survey